

ICRA 2026 Paper Title

Author 1¹ and Author 2²

Abstract—ICRA (IEEE International Conference on Robotics and Automation) is the premier robotics conference. This template follows IEEE conference formatting guidelines with a 6-page limit plus up to 2 optional extra pages.

I. INTRODUCTION

The page limit for ICRA is typically 6 pages, with an option to pay for up to 2 extra pages. Submissions are checked by PaperPlaza for margin compliance.

II. RELATED WORK

Discuss relevant prior work in robotics, automation, and related fields.

III. METHODOLOGY

Present your approach with appropriate formalism:

$$\tau = J^T(q)F$$

where τ is the joint torque, J is the Jacobian, and F is the end-effector force.

IV. EXPERIMENTS

Present experimental validation:

TABLE I
EXPERIMENTAL RESULTS

Method	Success Rate	Avg. Time (s)
Baseline	72%	15.3
Ours	91%	8.7

V. CONCLUSIONS

Summarize contributions and discuss future extensions.